# A New Econometric Approach for Modeling Several Count Variables: A Case Study of Crash Frequency Analysis by Crash Type and Severity

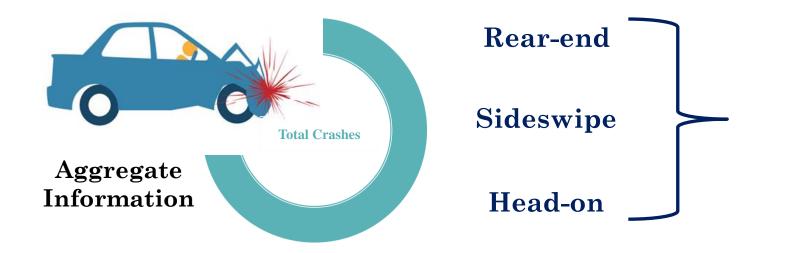
Naveen Eluru Professor, Department of Civil, Environmental and Construction Engineering University of Central Florida



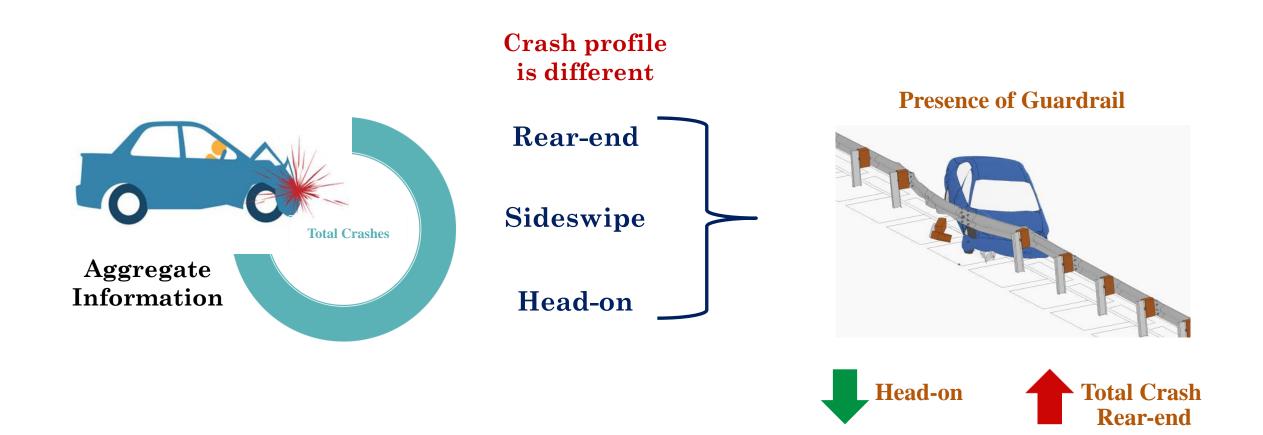
UNIVERSITY OF CENTRAL FLORIDA

















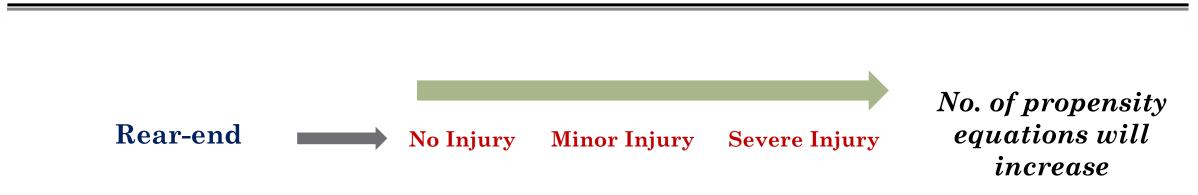




- We usually do not focus on all these dimensions
- Maximum: 3 crash types, 3 crash severities









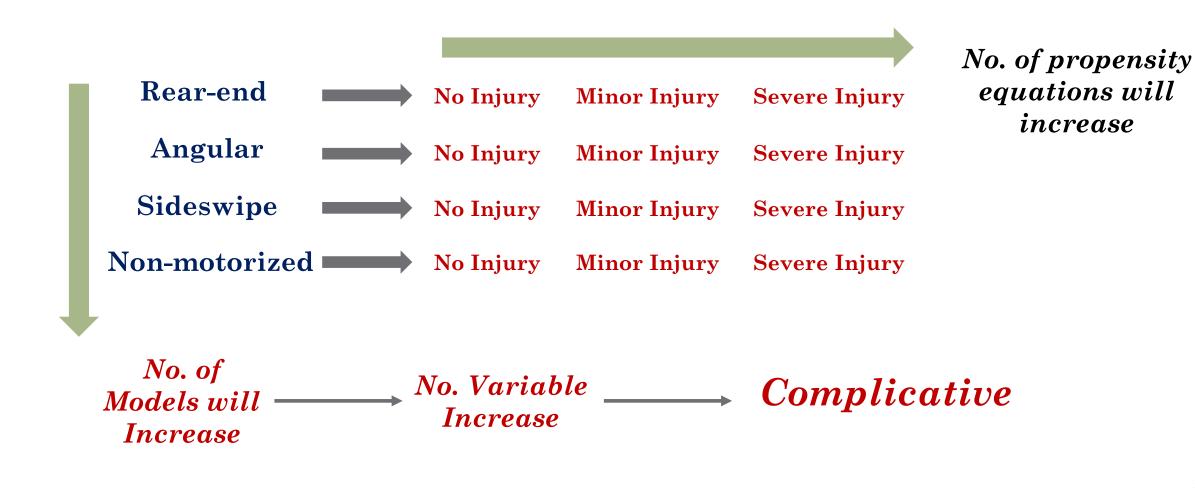




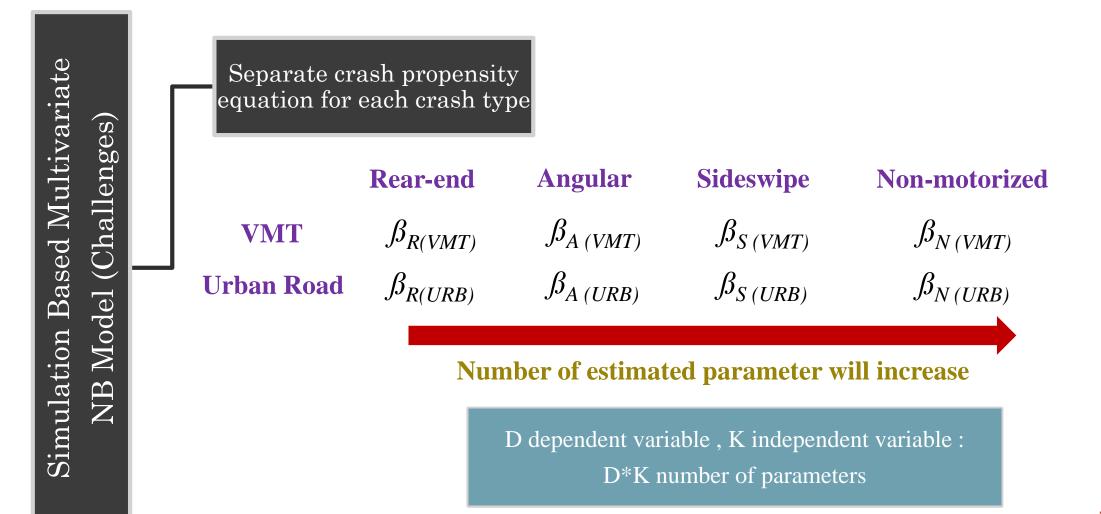
No. of propensity equations will increase



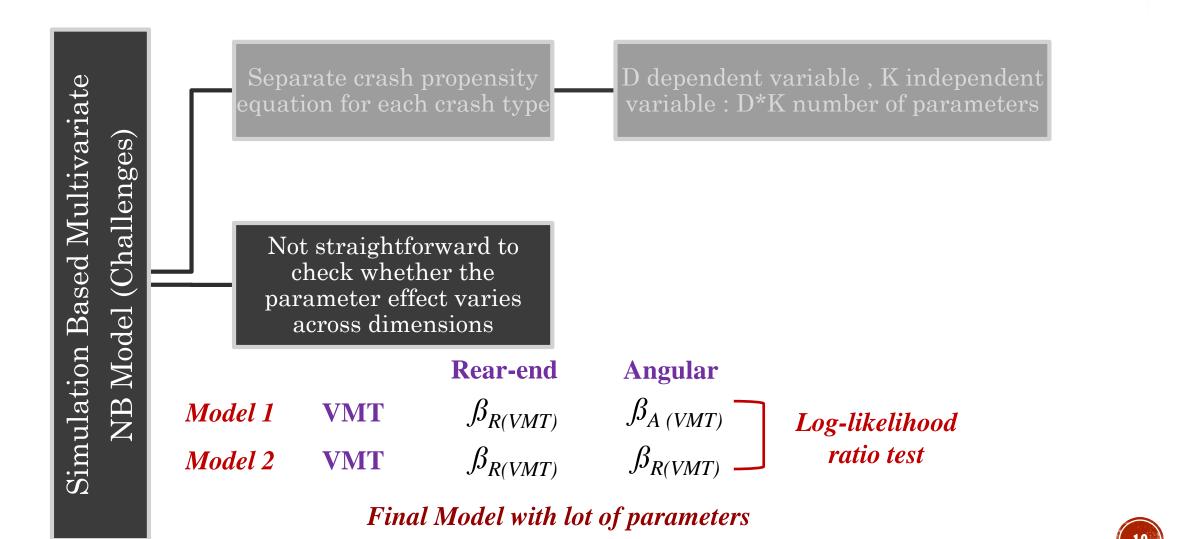


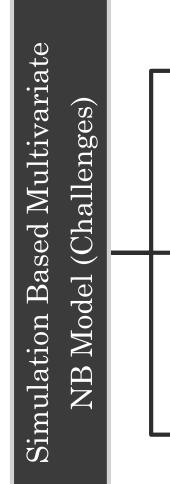












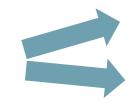
Separate crash propensity equation for each crash type

Not straightforward to check whether the parameter effect varies across dimensions D dependent variable , K independent variable : D\*K number of parameters

Need to perform log-likelihood ratio test for every parameter added

The final model associated with high number of parameters

Estimating unobserved factors requires simulation.



Number of Dimensions

Number of Unobserved Components



#### **Traditional Count Approach**

ID	TAZ	<b>Rear-end</b>	Angular	Sideswipe	Non-motorized	VMT
1	1	10	12	8	2	100

#### **Proposed Count Approach**

ID	TAZ	<b>Crash Type</b>	Crash	VMT
1	1	Rear-end	10	100
2	1	Angular	12	100
3	1	Sideswipe	8	100
4	1	Non-motorized	2	100



#### **Traditional Approach**

ID	TA	Z Rear-end	Ang	ular	Side	swipe	ľ	Non-motori	zed	VMT		
1	1	10	1	2		8		2		100		
Мо	del <sub>SW</sub>	$\beta_{S0} + \beta_{sV}^*$	VMT									
Pro	Proposed Count Approach Dummy Interaction											
ID	TAZ	<b>Crash Type</b>	Crash	VMT	Α	S	NM	VMT*A	VMT*S	VMT*NM		
1	1	Rear-end	10	100	0	0	0	0	0	0		
2	1	Angular	12	100	1	0	0	100	0	0		
3	1	Sideswipe	8	100	0	1	0	0	100	0		
4	1	Non-motorized	2	100	0	0	1	0	0	100		
M	odel	$\beta_0 + \beta_1 * V$	$VMT + \beta_2$	$\beta_2 *A + \beta_3$	*S + f	$B_4$ *NM	+ $\beta_6 * Vl$	$MT^*S + \beta_5 * VI$	$MT^*A + \beta_7^*$	VMT*NM		

 $\beta_{S0} = \beta_0 + \beta_3; \beta_{SV} = \beta_1 + \beta_6$ 



Pror	nosed S	Severity Appr	oach							
			oucii	Counts				Fractions		
ID	TAZ	Crash Type	Crash	PDO	Injury	Fatal	PDO	Injury	Fatal	
1	1	Rear-end	10	6	4	0	0.6	0.4	0	
2	1	Angular	12	6	<b>5</b>	1	0.5	0.42	0.08	
3	1	Sideswipe	8	<b>5</b>	2	1	0.63	0.25	0.12	
4	1	Non-motorized	4	0	3	1	0	0.75	0.25	

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#### **Proposed Approach**

ID	TAZ	<b>Crash Type</b>	Crash	PDO	Injury	Fatal	PDO	Injury	Fatal
1	1	Rear-end	10	6	4	0	0.6	0.4	0
2	1	Angular	12	6	5	1	0.5	0.42	0.08
3	1	Sideswipe	8	5	2	1	0.63	0.25	0.12
4	1	Non-motorized	4	0	3	1	0	0.75	0.25
Count Part Panel NB Model		- -		x		Orde	oportion ered Frac Split Mod	tional	
		Crash Typ	e				С	rash Seve	erity

Crash Counts of Each Severities by Crash Types



#### **Proposed Approach**

ID	TAZ	<b>Crash Type</b>	Crash	PDO	Injury	Fatal	PDO	Injury	Fatal
1	1	Rear-end	10	6	4	0	0.6	0.4	0
2	1	Angular	12	6	5	1	0.5	0.42	0.08
3	1	Sideswipe	8	5	2	1	0.63	0.25	0.12
4	1	Non-motorized	4	0	3	1	0	0.75	0.25

Count Part Panel NB Model	Advantage	Proportion Part Ordered Fractional Split Model
Crash Type	<ul> <li>A single model system</li> <li>2 components only</li> <li>Retain ordering nature</li> <li>Parsimonious Model set</li> </ul>	re of severities





### **MODELING FRAMEWORK**

Methodology (Joint Panel NB-GOPFS Model)

$$v_{ir} = E(y_{ir}|\mathbf{x}_{ir}) = exp\left(\left(\boldsymbol{\beta} + \boldsymbol{\theta}_i + \boldsymbol{\Phi}_{ir} \pm \eta_{irk}\right)\mathbf{x}_{ir} + \varepsilon_{ir}\right)$$
  

$$P(y_{ir}|v_{ir}, \lambda') = \frac{\Gamma\left(y_{ir} + \frac{1}{\lambda'}\right)}{\Gamma(y_{ir} + 1)\Gamma\left(\frac{1}{\lambda'}\right)} \left(\frac{1}{1 + \lambda'v_{ir}}\right)^{\frac{1}{\lambda'}} \left(1 - \frac{1}{1 + \lambda'v_{ir}}\right)^{y_{ir}}$$
  
NB Model

$$y_{irk}^{*} = (\alpha_{r} + \gamma_{irk} + \delta_{ir} \pm \eta_{irk})z_{ir} + \xi_{irk}$$
  

$$\psi_{rk} = \psi_{r,k-1} + exp((\beta_{rk} + \theta_{irk} + \varsigma_{ir} \pm \eta_{irk})s_{irk})$$
  

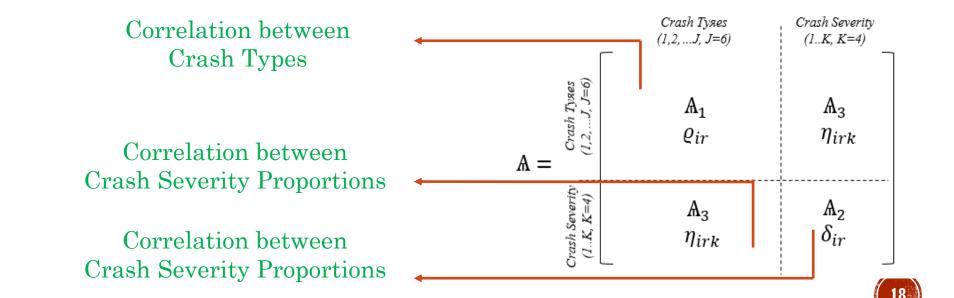
$$P_{irk} = G \left[(\psi_{rk} - \{(\alpha + \gamma_{i} + \delta_{irk} \pm \eta_{irk})z_{ir}\}\right] - G \left[(\psi_{r,k-1} - \{(\alpha + \gamma_{i} + \delta_{irk} \pm \eta_{irk})z_{ir}\}\right]$$
  
**GOPFS**  
**Model**



### **MODELING FRAMEWORK**

Methodology (Joint Panel NB-GOPFS Model)

$$L_{i} = \int_{\Omega} \prod_{r=1}^{R} \left[ \left( P(c_{ir}) \right) \times \prod_{k=1}^{K} (P_{irk})^{\varpi_{ir}d_{irk}} \right] d\Omega \qquad \text{Joint Model Estimation}$$

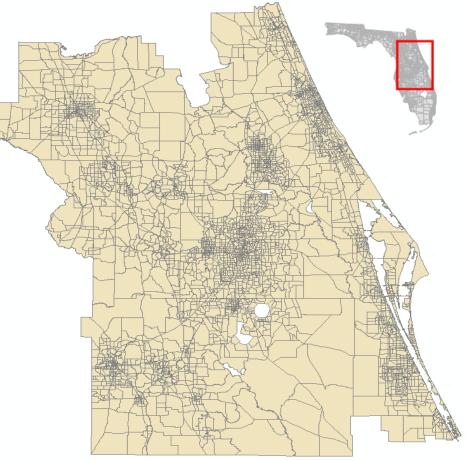


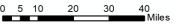


## STUDY AREA

#### Central Florida Region

- ➤ Total 11 counties
- Crash data- Year 2016
- □ 117K crashes
- **4**,747 TAZs
  - > 3,815 TAZs Estimation Sample
  - > 932 TAZs Validation Se
- □ Data source: FDOT, CARS, S

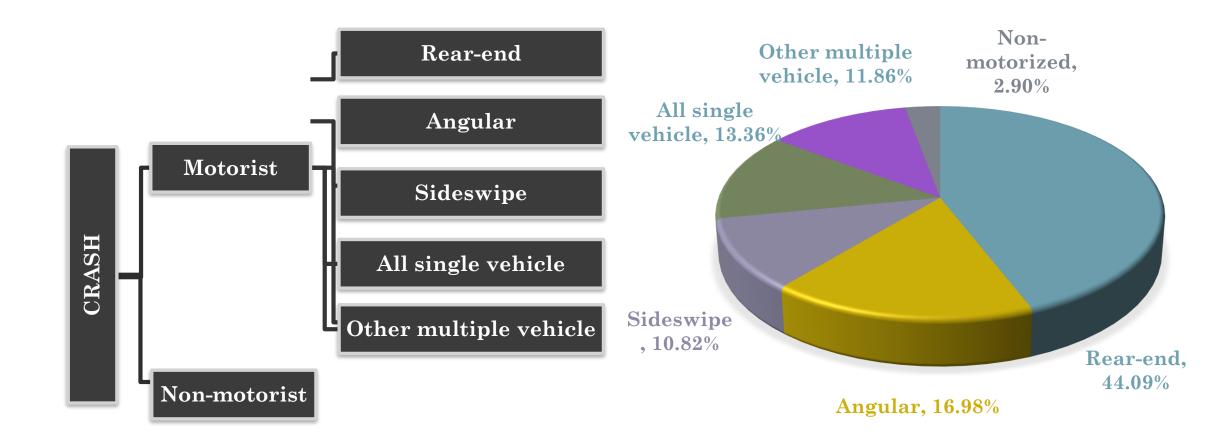






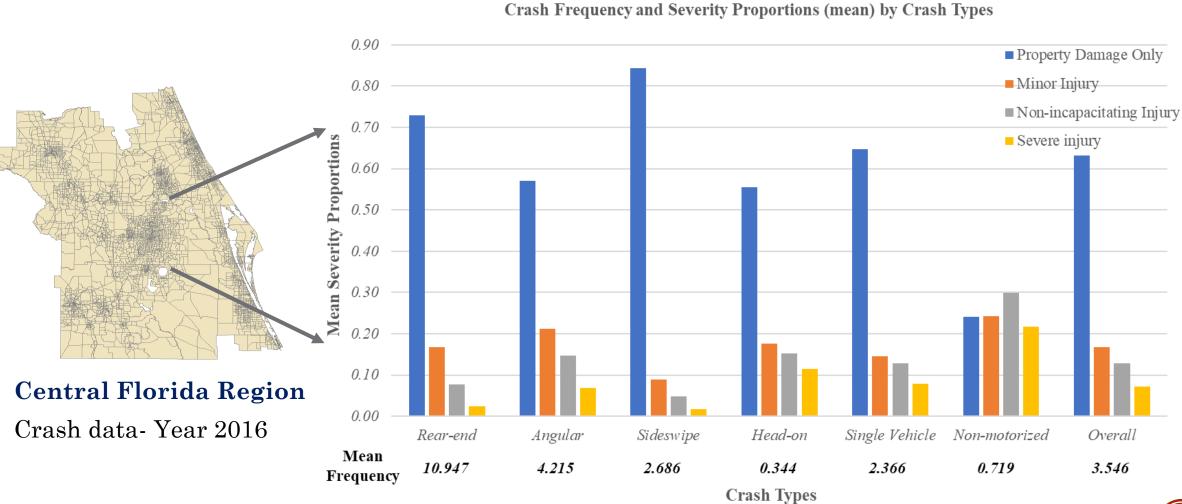


# DATA DESCRIPTION



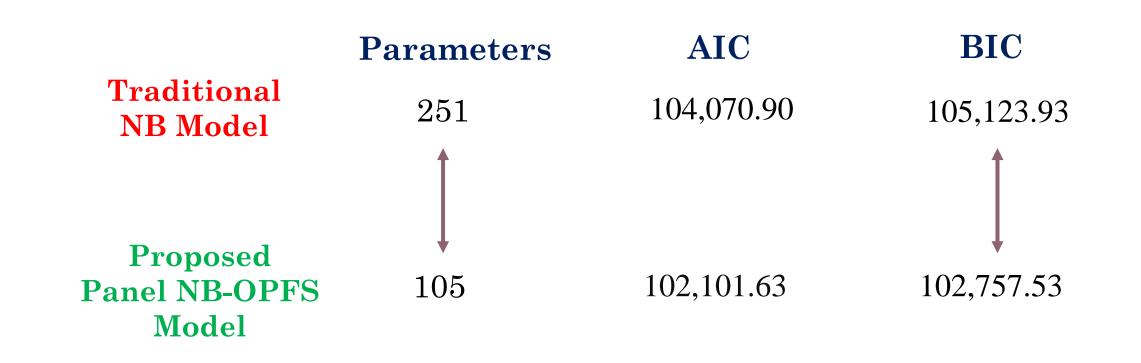


# DATA DESCRIPTION





#### MODEL FIT





	Overall		Deviations						
Variable	Crash Risk	Rear-end (1)	Angular (2)	Sideswipe (3)	Head-on (4)	Single Vehicle (5)	Non- motorized (6)		
				Deviation, Ove	erall) - N/I = Nerconstants	o Impact			
Roadway Characteristic									
Proportion of arterial roads	▲ (1,2,5,6)			N/I	N/I	▼,▼			
Number of intersections	▲ (2,4,6)	N/I		N/I		N/I			
Signal Intensity	▲ (1,3,5,6)		N/I	▼,▼	N/I	▼,▼			
Road length over 55mph	▲ (1-6)		▼,▼		▼,▼	▲,▲	▼,▼		
Variance of speed limit	<b>▲</b> (1-3)			▲,▲	N/I	N/I	N/I		
Road with median	▲ (1-4)				▼,▼	N/I	N/I		
Width of outside shoulder	▼ (1-5)		▼,▼	▼,▼		▲,▼	N/I		
Average sidewalk width	▼ (6)	N/I	N/I	N/I	N/I	N/I	▼		
Land Use Characteristic	-								
Urban area	▲ (1-4,6)			▼,▲	▼,▲	N/I	▼,▲		
Office area	▲ (1,3,6)		N/I		N/I	N/I	▼,▲		
Residential area	▼ (3,4)	N/I	N/I			N/I	N/I		

	Overall		Deviations						
Variable	Crash Risk	Rear-end (1)	Angular (2)	Sideswipe (3)	Head-on (4)	Single Vehicle (5)	Non- motorized (6)		
				Deviation, Ove	erall) - N/I = N	o Impact			
Land Use Characteristic									
Urban Area	▲ (1-4,6)			▼,▲	▼,▲	N/I	▼,▲		
<b>Positive</b> <b>Impact</b>	<b>Crash</b> types	Similar Effect	Imj		Still sitive	No Imj	pact		

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	Overall		Deviations							
Variable	Crash Risk	Rear-end (1)	Angular (2)	Sideswipe (3)	Head-on (4)	Single Vehicle (5)	Non- motorized (6)			
				(Deviation, Ov	erall) – N/I = N	o Impact				
Built Environment Characteris	tic									
No. of restaurants	▲ (13,6)		N/I	▼,▲	N/I	N/I	▼,▲			
No. of shopping centers	▲ (1,3)		N/I		N/I	N/I	N/I			
Traffic Characteristic										
VMT	▲ (2-4,6)	N/I		▲,▲	▲ , ▲	N/I	▼,▲			
Truck VMT	▲ (1,5)		N/I	N/I	N/I	▲,▲	N/I			
Socio-demographic Characteri	stic	•								
Non-motorist commuters	▲ (1-3,6)		▲,▲	▲,▲	N/I	N/I				
Transit Users	▲ (1,6)		N/I	N/I	N/I	N/I				
Random Parameters				•						
Road with speed over 55mph	– Angular Cras	sh								

### **MODEL RESULTS (GOPFS PART)**

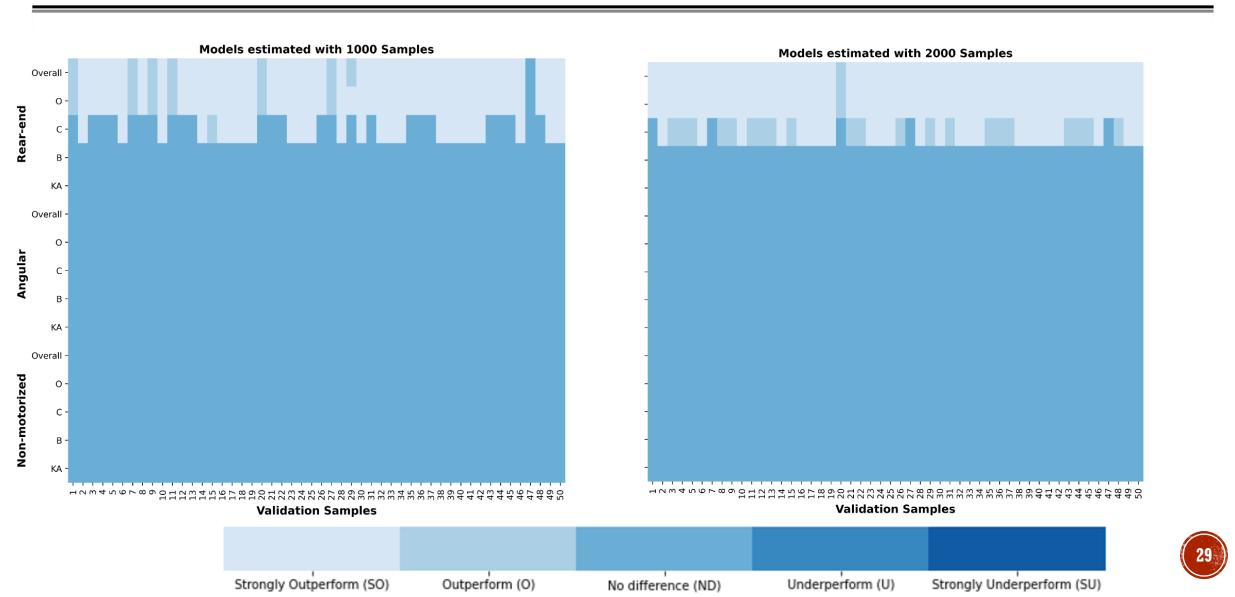
	Overall Severity Risk	Deviations							
Variable		Rear-end (1)	Angular (2)	Sideswipe (3)	Head-on (4)	Single Vehicle (5)	Non- motorized (6)		
				(Deviation, Ove	erall) – N/I = No	o Impact			
Roadway Characteristic									
Proportion of arterial roads	▲ (1,2,5)		▲,▲	N/I	N/I		N/I		
Possible and NIC injury		V	N/I	N/I	N/I	N/I	N/I		
Local Roads	▼ (4,6)	N/I	N/I	N/I		N/I			
Number of intersections	▼ (4,5)	N/I	N/I	N/I			N/I		
Signal Intensity	▼ (2-4)	N/I				N/I	N/I		
Width of inside shoulder	▼ (3)	N/I	N/I		N/I	N/I	N/I		
Width of outside shoulder	<b>V</b> (1)		N/I	N/I	N/I	N/I	N/I		
Road length over 55mph	▲ (1,2,4-6)			N/I	▲,▲				
NIC and Severe injury		▼	N/I	N/I	N/I	N/I	N/I		
Poor Pavement Condition	▲ (3)	N/I	N/I		N/I	N/I	N/I		
Land Use Characteristic									
Urban area	▲ (1-4,6)			▼,▲	▼,▲	N/I	▼,▲		
Office area	▲ (1,3,6)		N/I		N/I	N/I	▼,▲		
Residential area	▼ (3,4)	N/I	N/I			N/I	N/I		

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	Overall		Deviations							
Variable	Severity Risk	Rear-end (1)	Angular (2)	Sideswipe (3)	Head-on (4)	Single Vehicle (5)	Non- motorized (6)			
				(Deviation, Ove	erall) - N/I = Nerall	o Impact				
Built Environment Characteri	Built Environment Characteristic									
No. of commercial centers	▼ (6)	N/I	N/I	N/I	N/I	N/I				
No. of recreational centers	▼ (1)		N/I	N/I	N/I	N/I	N/I			
No. of restaurants	▼ (5)	N/I	N/I	N/I	N/I		N/I			
NIC and Severe injury		N/I	N/I	N/I	N/I		N/I			
No. of shopping centers	▼ (2-4)	N/I				N/I	N/I			
Possible and NIC injury		N/I	N/I	<b></b>	N/I	N/I	N/I			
Traffic Characteristic		-	-	-						
Congested condition	▼ (1-2)			N/I	N/I	N/I	N/I			
NIC and Severe injury		N/I		N/I	N/I	N/I	N/I			
Truck VMT	▲ (3,4)	N/I	N/I			N/I	N/I			

Variable	Overall Severity Risk	Deviations					
		Rear-end (1)	Angular (2)	Sideswipe (3)	Head-on (4)	Single Vehicle (5)	Non- motorized (6)
		(Deviation, Overall) $- N/I = No$ Impact					
Socio-demographic Characteristic							
Employee	▼ (6)	N/I	N/I	N/I	N/I	N/I	
Motorcycle users	▲ (2)	N/I		N/I	N/I	N/I	N/I
Senior people (>65)	▼ (6)	N/I	N/I	N/I	N/I	N/I	
HH with no cars	▲ (6)	N/I	N/I	N/I	N/I	N/I	

### MODEL VALIDATION



University of Central Florida

# SUMMARY AND CONCLUSION

#### Current Research

#### A joint model for crash types and severities

Panel NB-GOPFS model

- Only need 2 propensity equations
- Less computational time

*Advantage* 

- Parsimonious specification
- Can predict several dimensions

#### **Findings**

Good performance for both sample





#### PAPER

 Bhowmik T., S. Yasmin and N. Eluru (2021). "A New Econometric Approach for Modeling Several Count Variables: A Case Study of Crash Frequency Analysis by Crash Type and Severity", Transportation Research Part B Volume 153, November 2021, Pages 172-203

